## EXPAND YOUR VISION

## Mastering real-world materials using bidirectional texture functions

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#### OREALIA™

Interactive photo-realistic 3D digital prototyping

Luc Claustres – Technical Director



- Onesia develops and markets real time interactive photorealistic 3D rendering for computer-aided design, scientific visualization, and industries that require virtual prototyping
- Orealia<sup>™</sup> is the first entry-level virtual prototyping solution offering the power of high-end 3D rendering softwares

#### orgalia - Adressed problems

Product design is too slow

 *reduce time to market*

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- Costs of Physical prototypes are too high
  ✓ no longer required
- The interaction between Production and Marketing departments is difficult
   ✓ user-friendly interface to share data
- The quality of the output is not realistic
  ✓ enough to be used "out of the box"







 Goal : capture the appearance of real-world materials and apply it to virtual prototypes in real-time



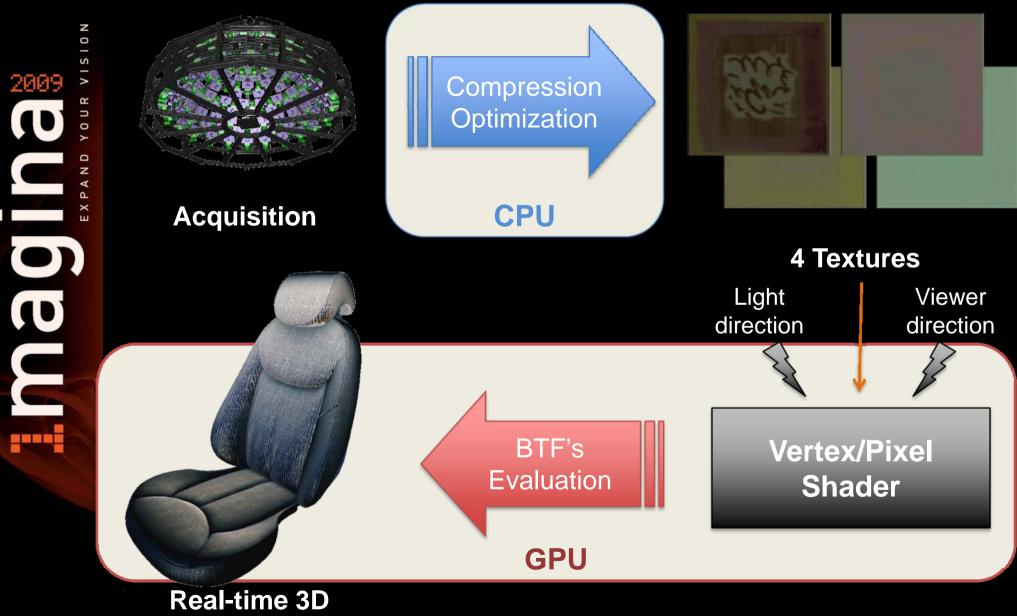
Single texture (photograph)

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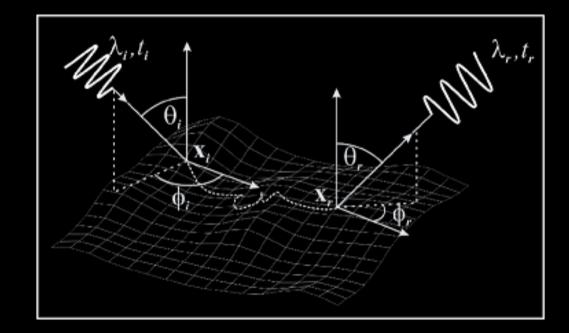
- x simple/but unrealistic : flat appearance
- Textures for different lighting/viewing configurations
  ✓ realistic : reflection, anisotropy and self-shadowing

#### Srealia - BTF overview



Visualization



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We need to simplify

 $\checkmark t_i = t_r, \ \lambda_i = \lambda_r, \ x_i = x_r \rightarrow BTF$ 

 $\checkmark$  if invariant with respect to x (plain color)  $\rightarrow$  BRDF

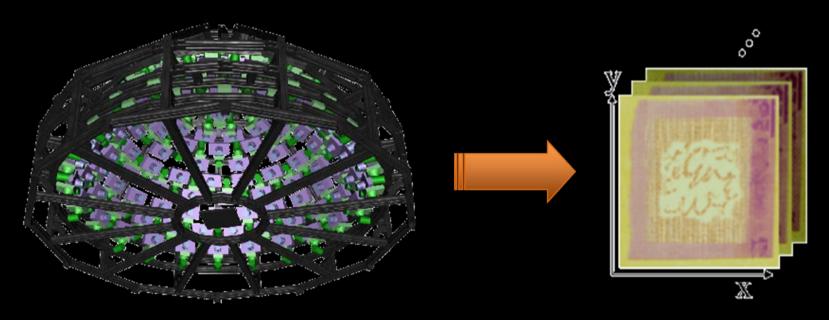


Measurement device example

- ✓ 151 digital consumer cameras (Canon PowerShot A75)
- $\checkmark$  2/3 measurements per day

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post-processing required for shiny materials like paint



Generates a huge amount of data
 ✓ 81x81 lighting/viewing directions - 256x256 = 1,3 GB



- BTF viewed as a spatial-varying BRDF [McAlliste et al.]
- For each pixel we use the Lafortune's model

$$f_{r}(\omega_{i} \rightarrow \omega_{r}) = \rho_{d} + \sum_{j} \rho_{s,j} \begin{bmatrix} \omega_{r,x} \\ \omega_{r,x} \\ \omega_{r,x} \end{bmatrix} \begin{bmatrix} C_{j,x} \\ C_{j,y} \\ C_{j,z} \end{bmatrix} \begin{bmatrix} \omega_{i,x} \\ \omega_{i,x} \\ \omega_{i,x} \end{bmatrix} \end{bmatrix}^{n_{j}}$$

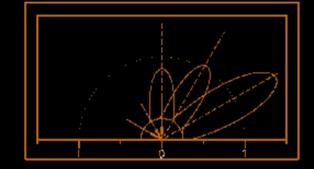
- $\checkmark$  Generalise the Phong's model
- ✓ Non-linear

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✓ Anisotropic



✓ Adapted to a wide range of materials



Parameter estimation

BTF(x, 
$$\omega_i, \omega_r) \approx \rho_d + \sum_j \rho_{s,j} (\omega_r^t \cdot C_j \cdot \omega_i)^{(1)} + (s(x)) \cdot H$$

- 1. Diffuse component :  $\rho_d$  = minimum of all values
- 2. Albedo simplification :  $\rho_s$  is common to all lobes
- 3. Lobes : find best  $C_{x,j}$ ,  $C_{y,j}$ ,  $C_{z,j}$ ,  $n_j$  (j < 3)
  - Levenberg-Marquardt non-linear optimisation
- 4. Residual s(x) to model the error
  ✓ least square approximation of BTF(x, ω<sub>i</sub>, ω<sub>r</sub>) f<sub>r,x</sub>(ω<sub>i</sub>, ω<sub>r</sub>)



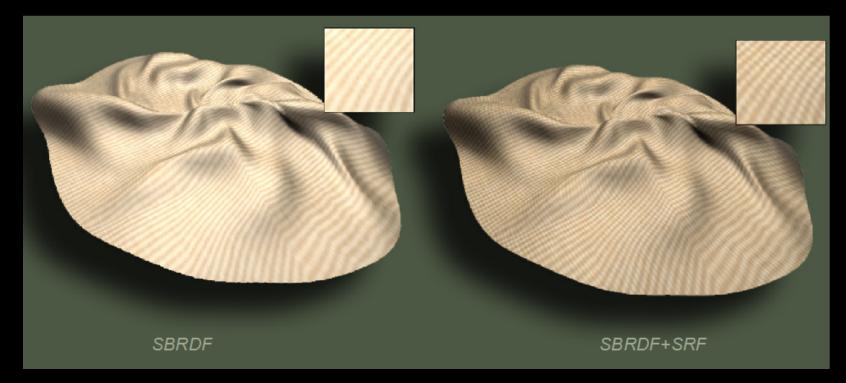
#### Performed through a vertex/fragment shader

1. Retrieve texture coordinates

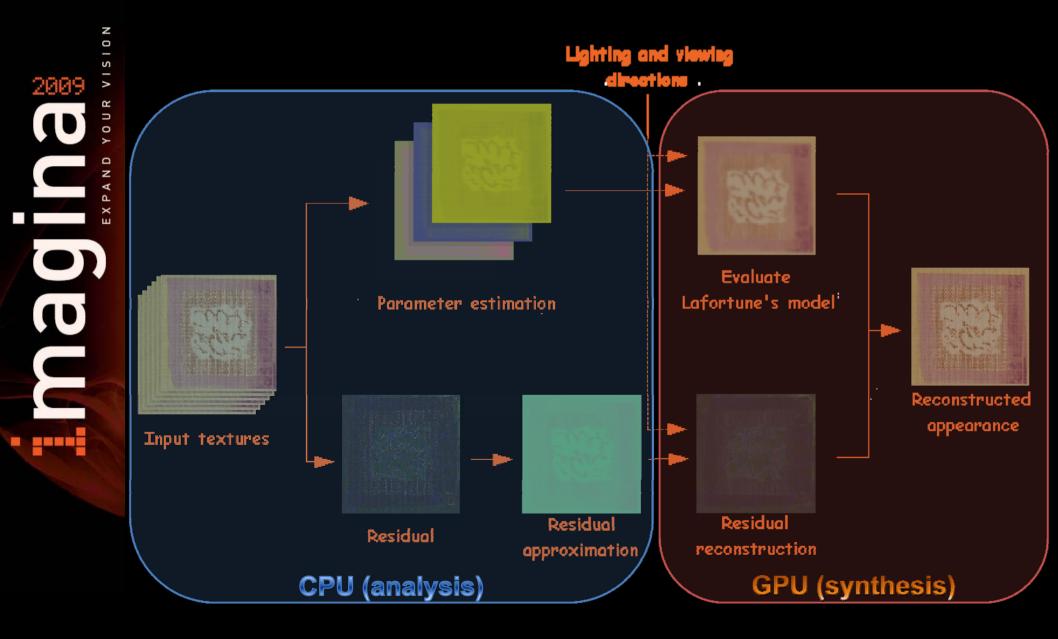
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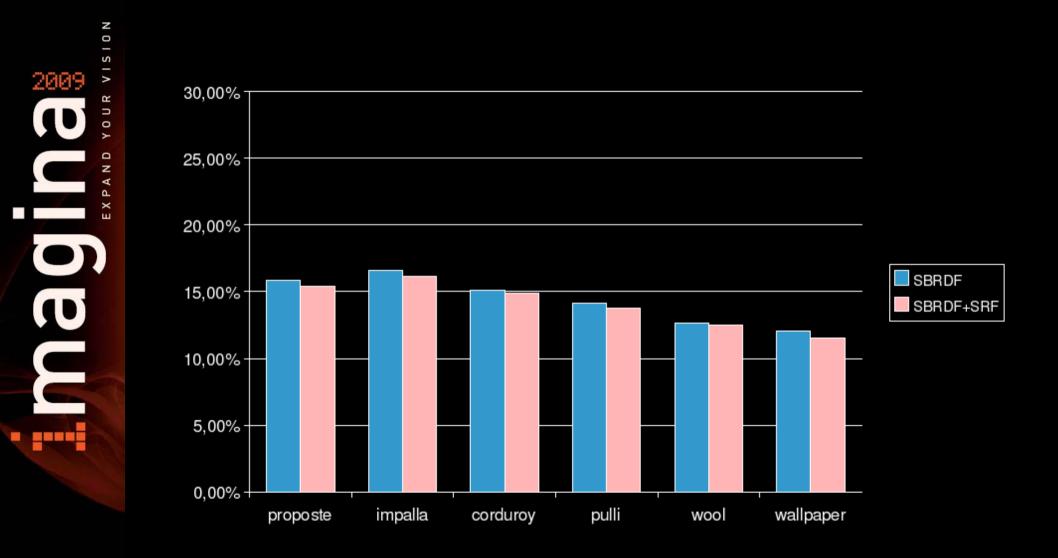
- 2. Filter parameters stored in textures accordingly
- 3. Compute light/viewing configuration
- 4. Evaluate Lafortune's model + residual accordingly
- 5. Evaluate the rendering equation (sum up light contributions)



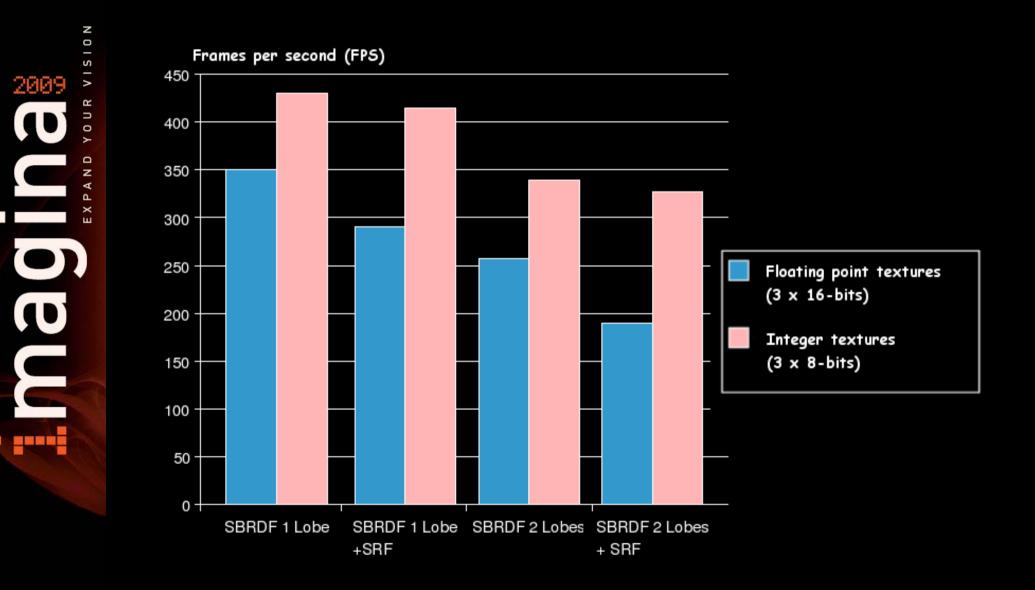
#### orgalig - BTF pipeline summary



#### Srealig - Results (error)



#### Srealig - Results (speed)



### Srealia - Results (demo)

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- This work is based on a technological transfer
  ✓ partnership with IRIT/UPS/CNRS (Toulouse France)
- This work used public data
  ✓ provided by the Graphics Lab at Bonn University



#### THANKS FOR YOUR ATTENTION

# You are welcome at ONESIA booth B8

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